Notice of Allowability	Application No.	Applicant(s)
	10/729,104	PRAKAH-ASANTE ET AL.
	Examiner	Art Unit
	Gary Chin	3661
The MAILING DATE of this communication app All claims being allowable, PROSECUTION ON THE MERITS IS herewith (or previously mailed), a Notice of Allowance (PTOL-85) NOTICE OF ALLOWABILITY IS NOT A GRANT OF PATENT R of the Office or upon petition by the applicant. See 37 CFR 1.313 1. This communication is responsive to the amendment filed 2. The allowed claim(s) is/are 1-4, 7-13 and 15-18. 3. Acknowledgment is made of a claim for foreign priority unally all by Some* c) None of the: 1. Certified copies of the priority documents have 2. Certified copies of the priority documents have 3. Copies of the certified copies of the priority documents have 3. Copies of the certified copies of the priority documents have 3. Certified copies not received: **Certified copies not received:** Applicant has THREE MONTHS FROM THE "MAILING DATE" noted below. Failure to timely comply will result in ABANDONN THIS THREE-MONTH PERIOD IS NOT EXTENDABLE. 4. A SUBSTITUTE OATH OR DECLARATION must be subminsformal patents.	is (OR REMAINS) CLOSED in or other appropriate communiting the communiting that is a second to the communities of this communication to file MENT of this application. In the communication to file MENT of this application. In the communication to file of this communication.	this application. If not included nication will be mailed in due course. THIS ubject to withdrawal from issue at the initiative of the first of the initiative of the initiati
 CORRECTED DRAWINGS (as "replacement sheets") must (a) ☐ including changes required by the Notice of Draftspers 		(PTO-948) attached
1) hereto or 2) to Paper No./Mail Date	_	(· · · · · · · · · · · · · · · · · · ·
(b) ☐ including changes required by the attached Examiner' Paper No./Mail Date Identifying indicia such as the application number (see 37 CFR 1	l.84(c)) should be written on th	e drawings in the front (not the back) of
each sheet. Replacement sheet(s) should be labeled as such in to 6. DEPOSIT OF and/or INFORMATION about the deposit attached Examiner's comment regarding REQUIREMENT	sit of BIOLOGICAL MATE	RIAL must be submitted. Note the
Attachment(s) 1. ☐ Notice of References Cited (PTO-892)	5 Notice of Info	ormal Patent Application
2. ☐ Notice of Draftperson's Patent Drawing Review (PTO-948)	6. 🔲 Interview Su	mmary (PTO-413),
3. Information Disclosure Statements (PTO/SB/08),	7. Examiner's A	/lail Date nmendment/Comment
Paper No./Mail Date 4. Examiner's Comment Regarding Requirement for Deposit of Biological Material	8. ☐ Examiner's \$	Statement of Reasons for Allowance
	<u>-</u>	GARY CHIN PRIMARY EXAMINER

AMENDMENTS TO THE CLAIMS

In the set of claims within the Application, please retain, amend, or cancel each claim as hereinafter indicated.

1. (Currently Amended) A safety system for a vehicle as in claim 15, said safety system further comprising:

an occupant sensor located onboard said vehicle and operable to generate an occupant characteristic signal;

- a plurality of discretized patch sensors coupled to a peripheral area of said vehicle and operable to generate at least one collision detection signal; and
- a controller coupled to said occupant sensor and said plurality of discretized patch sensors;

wherein said controller is <u>coupled to said occupant sensor and</u> operable to determine an occupant status in response to said occupant characteristic signal[[,]] determine a collision type in response to said at least one collision detection signal[[,]] and <u>also</u> perform at least one countermeasure in response to <u>both</u> said occupant status and said collision type.

- 2. (Currently Amended) A safety system as in claim [[1]] 15, wherein said plurality of collision detection sensors includes discretized patch sensors that are at least partially formed of a poly-vinylidine fluoride material.
- 3. (Currently Amended) A safety system as in claim [[1]] <u>15</u>, wherein said plurality of <u>collision detection sensors includes</u> discretized patch sensors <u>that</u> are in a composite form.
- 4. (Currently Amended) A safety system as in claim [[1]] 15, wherein said plurality of discretized patch collision detection sensors are coupled to a bumper of said vehicle.

- 5. (Canceled)
- 6. (Canceled)
- 7. (Currently Amended) A safety system as in claim [[5]] 10, wherein said collision contact location estimator is operable to determine said collision contact location relative to said plurality of discretized patch sensors in response to values selected from at least one of a plurality of location threshold values, time synchronized comparative magnitude values, and signature values of the collision detection signals.
- 8. (Currently Amended) A safety system as in claim [[5]] 10, wherein said collision contact location estimator is operable to determine said collision contact location relative to said plurality of discretized patch sensors in response to at least one collision confirmation threshold value.
- 9. (Currently Amended) A safety system for a vehicle as in claim 15, said safety system further comprising:

an occupant sensor located onboard said vehicle and operable to generate an occupant characteristic signal;

a plurality of collision detection sensors coupled to the periphery of said vehicle and operable to generate at least one collision detection signal; and

wherein [[a]] said controller is coupled to said occupant sensor, and said plurality of collision detection sensors and comprising (i) a collision contact location estimator for determining a collision type, which includes determining a collision severity and a collision contact location on said vehicle, in response to said at least one collision detection signal, and (ii) a coordinated device activation system for performing is operable to perform at least one countermeasure in response to both said occupant characteristic signal and said collision type.

- 10. (Currently Amended) A safety system as in claim [[9]] 15, wherein said plurality of collision detection sensors are in the form of a plurality of discretized patch sensors.
- 11. (Currently Amended) A safety system as in claim [[9]] 15, wherein said plurality of collision detection sensors are at least partially formed of a poly-vinylidine fluoride material.
- 12. (Currently Amended) A safety system as in claim [[10]] <u>15</u>, wherein said plurality of <u>discretized patch</u> <u>collision detection</u> sensors are in a composite form.
- 13. (Currently Amended) A safety system as in claim [[9]] <u>15</u>, wherein said plurality of collision detection sensors are non-accelerometer type sensors.

14. (Canceled)

15. (Previously Presented) A safety system for a vehicle, said safety system comprising:

a plurality of collision detection sensors coupled to the periphery of said vehicle and operable to generate at least one collision detection signal; and

a controller coupled to said plurality of collision detection sensors and comprising (i) a collision contact location estimator for determining a collision type, which includes determining a collision severity and a collision contact location on said vehicle, in response to said at least one collision detection signal, and (ii) a coordinated device activation system for performing at least one countermeasure in response to said collision type;

wherein said collision contact location estimator, in determining said collision severity, is operable to generate at least one collision severity signal corresponding to

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approximately $K_i V_i (1-e^{-\tau t})$, in which V_i is voltage output from the i^{th} collision detection sensor, K_i is an adaptive gain, and τ is an adjustable filter time-constant.

- 16. (Currently Amended) A safety system as in claim [[9]] 15, wherein said collision contact location estimator is operable to determine said collision contact location relative to said plurality of collision detection sensors in response to values selected from at least one of a plurality of location threshold values, time synchronized comparative magnitude values, and signature values of the collision detection signals.
- 17. (Currently Amended) A safety system as in claim [[9]] 15, wherein said collision contact location estimator is operable to determine said collision contact location relative to said plurality of collision detection sensors in response to at least one collision confirmation threshold value.
- 18. (Previously Presented) A safety system as in claim 17, wherein said coordinated device activation system is operable to perform said at least one countermeasure based on the contacted area of said vehicle when said collision confirmation threshold value is exceeded.
 - 19. (Canceled)
 - 20. (Canceled)